IN THE SPECIFICATION

Please replace paragraph 4 on page 3 of the specification with the following paragraph.

B

[[In a third aspect,]] An aspect of the present invention [[relates to a]] is the movable diaphragm [[for a miniature actuator]], said movable diaphragm comprising, in the plane of the diaphragm

- a substantially stiff centre part,
- a resilient outer part surrounding the substantially stiff centre part,

where in the movable diaphragm shows predetermined magnetic properties, said predetermined magnetic properties varying across the substantially stiff centre part and the resilient outer part so as to avoid saturation effects of the movable diaphragm when the movable diaphragm is positioned in a magnetic flux that varies in the plane of the diaphragm.

Please replace paragraph 2 on page 5 of the specification with the following paragraph.

 b^2

[[According to the third aspect, the]] The movable diaphragm may further comprise a plurality of canals adapted to guide air from the centre part of the movable diaphragm to the outer part of the movable diaphragm so as to avoid squeeze film damping effects.

Please replace paragraph 3 on page 6 of the specification with the following paragraph.

 \mathbb{B}^3

In figure 1 the outer ring, i.e. the spacer chip 14 is a rectangular, O-shaped, soft magnetic metal ring. The permanent magnets 11 are positioned in the centre of the planar coils 13, lengthened by the soft magnetic material stamps 16.